



# Power Loss Recovery for NAND Flash Memories

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- Problem State
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- *PLR* Schemes using Per-Page Spare Areas with No Synchronization Overhead
- Summary

# Data and Meta-Data Synchronization

			Backup Cost Effectiveness	Recovery Cost Effectiveness	Recovery Coverage
Recovery-based Approach	Host System	Transaction-level Sync	★★★☆☆	★☆☆☆☆ <b>Challenge (should be cost effective – common case)</b>	★☆☆☆☆
		Transaction-level Sync	★★★★☆☆	★★★★★☆☆	★★★☆☆☆☆
	Storage System	Spare Areas	★★★★★☆☆	★☆☆☆☆☆☆	★★★★★☆☆
		Dedicated Blocks (Map Blocks)	★☆☆☆☆☆☆	★★★★★☆☆	★★★☆☆☆☆
		Hybrid (Combinational of Both)	★★★★☆☆☆☆	★★★★★☆☆	★★★★★☆☆
Prevention-based Approach	Battery	Capacitor	★★★★☆☆☆☆	★★★★★☆☆	★★★★★☆☆
		No	★☆☆☆☆☆☆	★★★★★☆☆	★★★★★☆☆
	Non-volatile Memory	NVRAM	★★★★☆☆☆☆	★★★★★☆☆	★★★★★☆☆

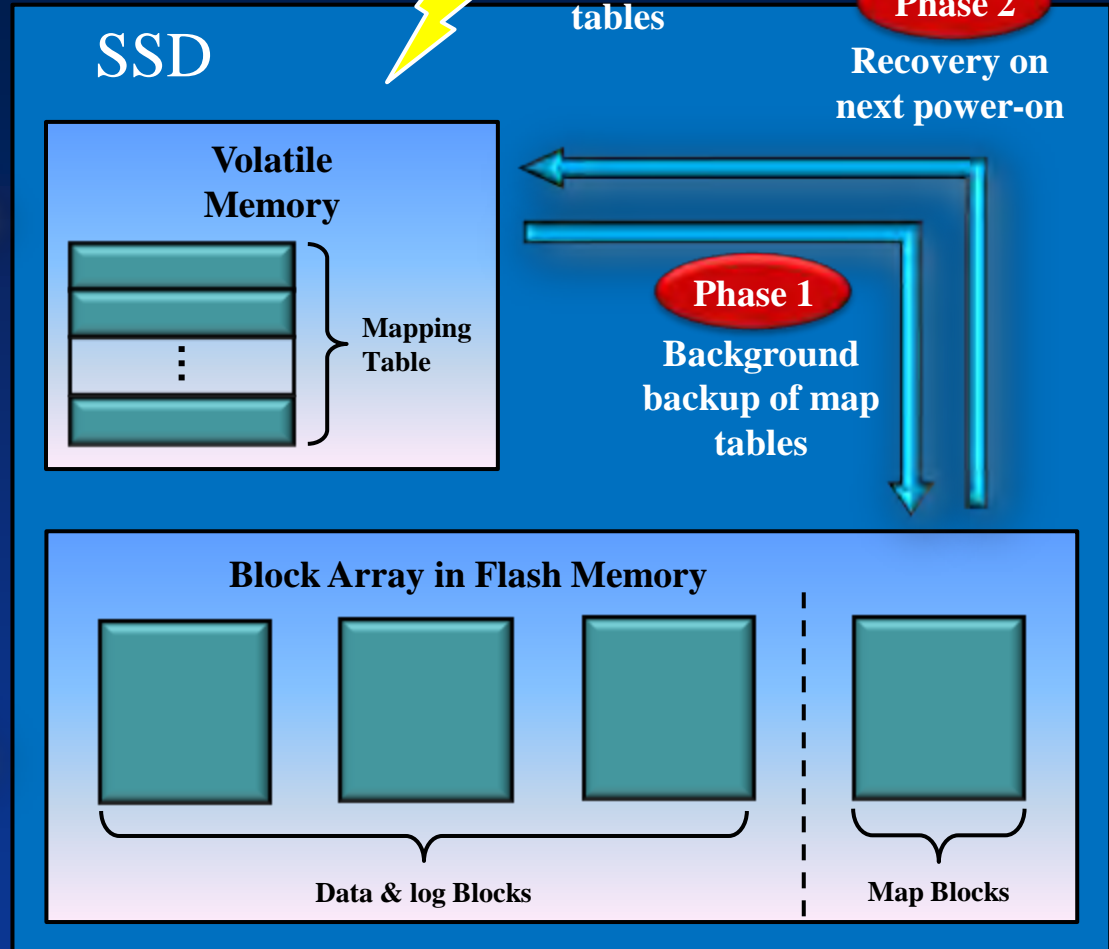
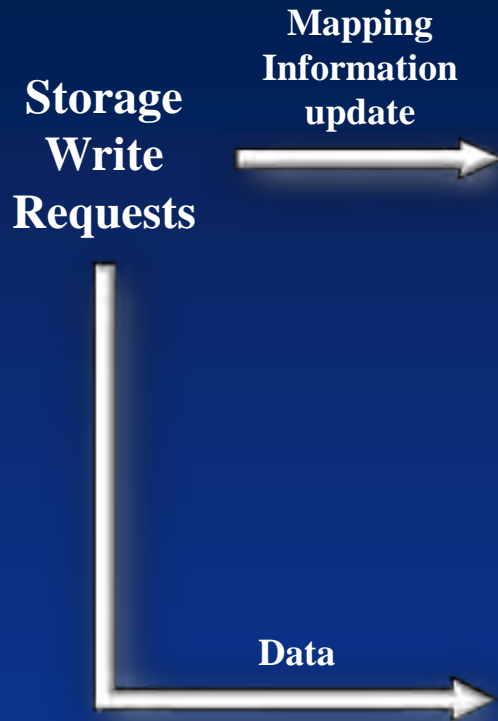
**Our focus (SSD internal architecture & algorithm)**

**Challenge (should be cost effective – common case)**

**Additional cost (needs hardware support)**

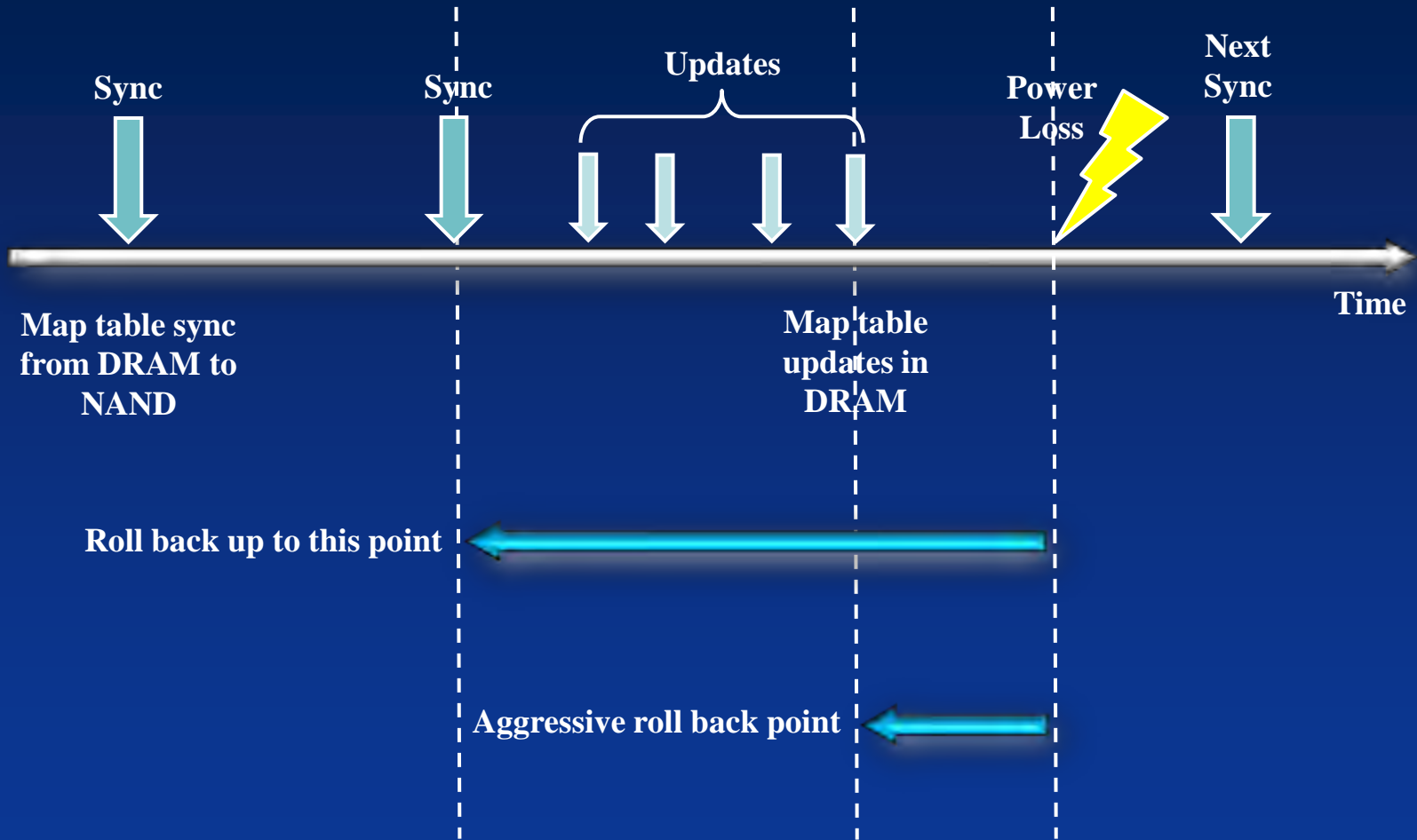
# PLR Introduction

Power Loss before background backup

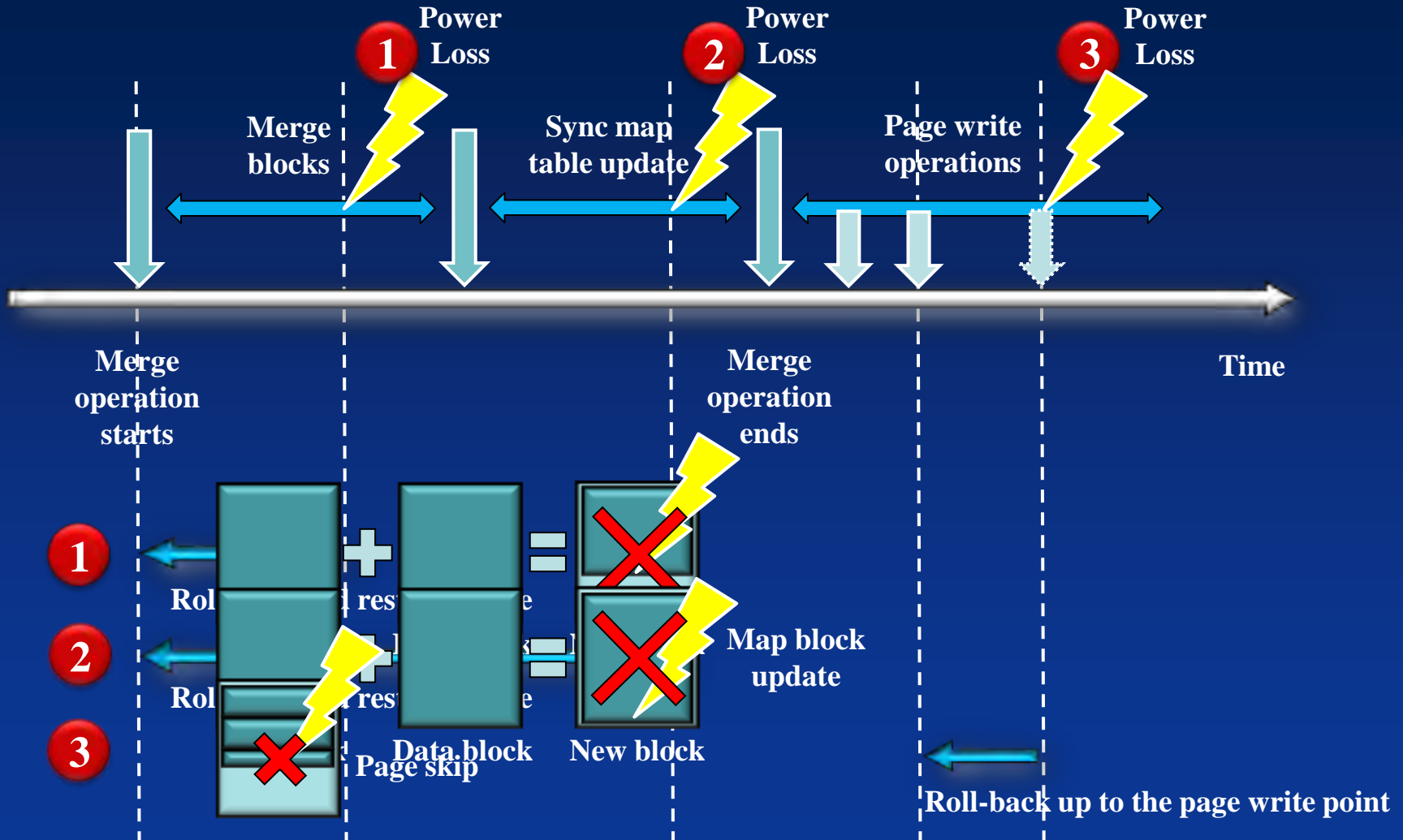


**How to make mapping tables as consistent as possible with backups in NAND Flash?**

# Power Loss Recovery



# Hybrid Mapping: A Case Study





## Problem Statement

- Run-Time Backup Cost Growth
  - Map table backup overhead: approximately 5% of write operation in normal case
- Merge Operations causes Changes in Map Table
  - Dependent upon FTL algorithms and workloads
- A Cost Effective Solution: Mapping Information Backup using Per-Page Spare Areas

**Power loss is a RARE event**  
**Make common case fast!!**



# Design Considerations

- *Run-Time Backup Cost*
  - Map table backup time from DRAM to NAND at run-time
  
- *Time for Recovery*
  - Map table reconstruction time from NAND to DRAM when a system re-boots after the power loss event
  
- *Recovery Coverage*
  - Restore data writes as complete as possible

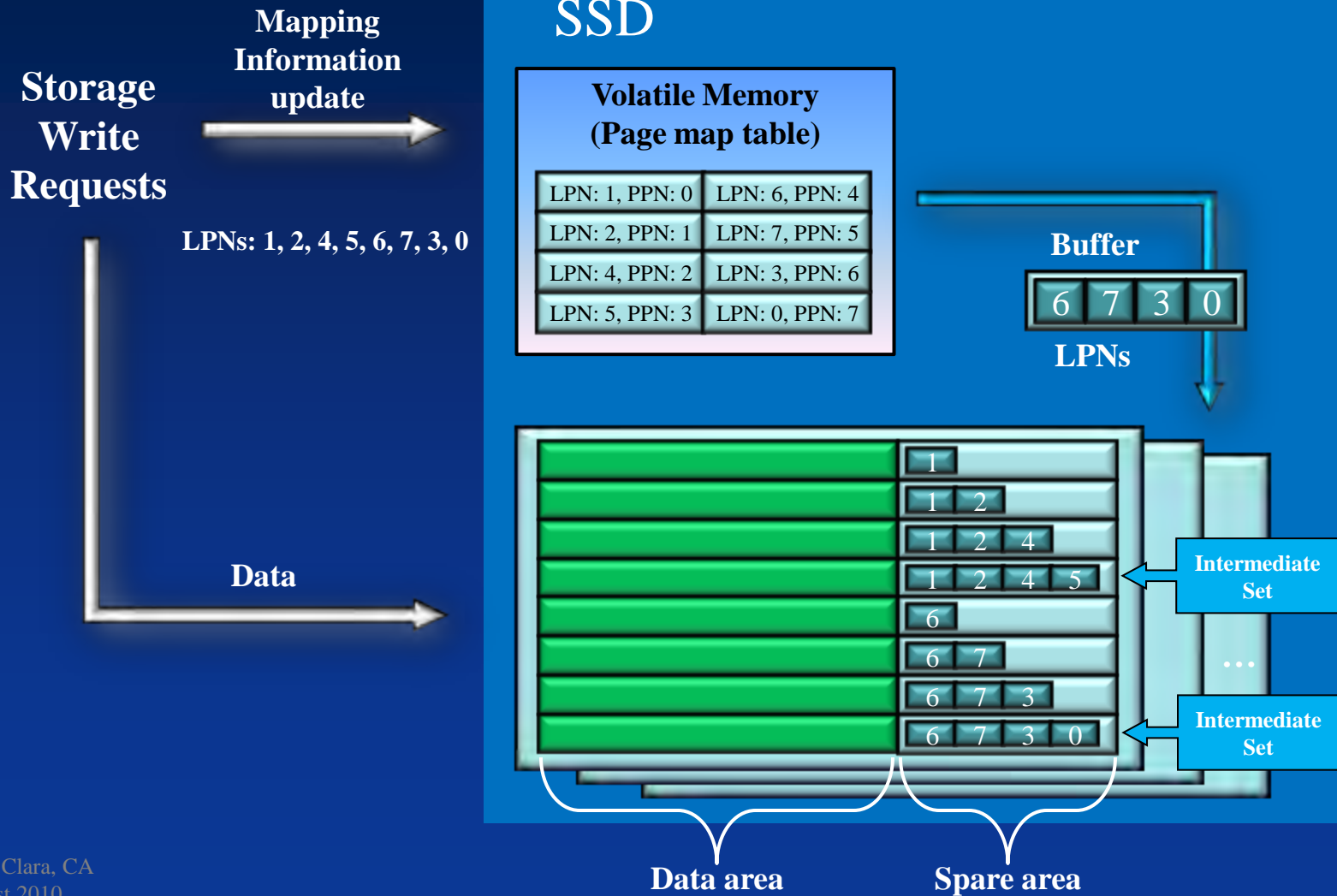




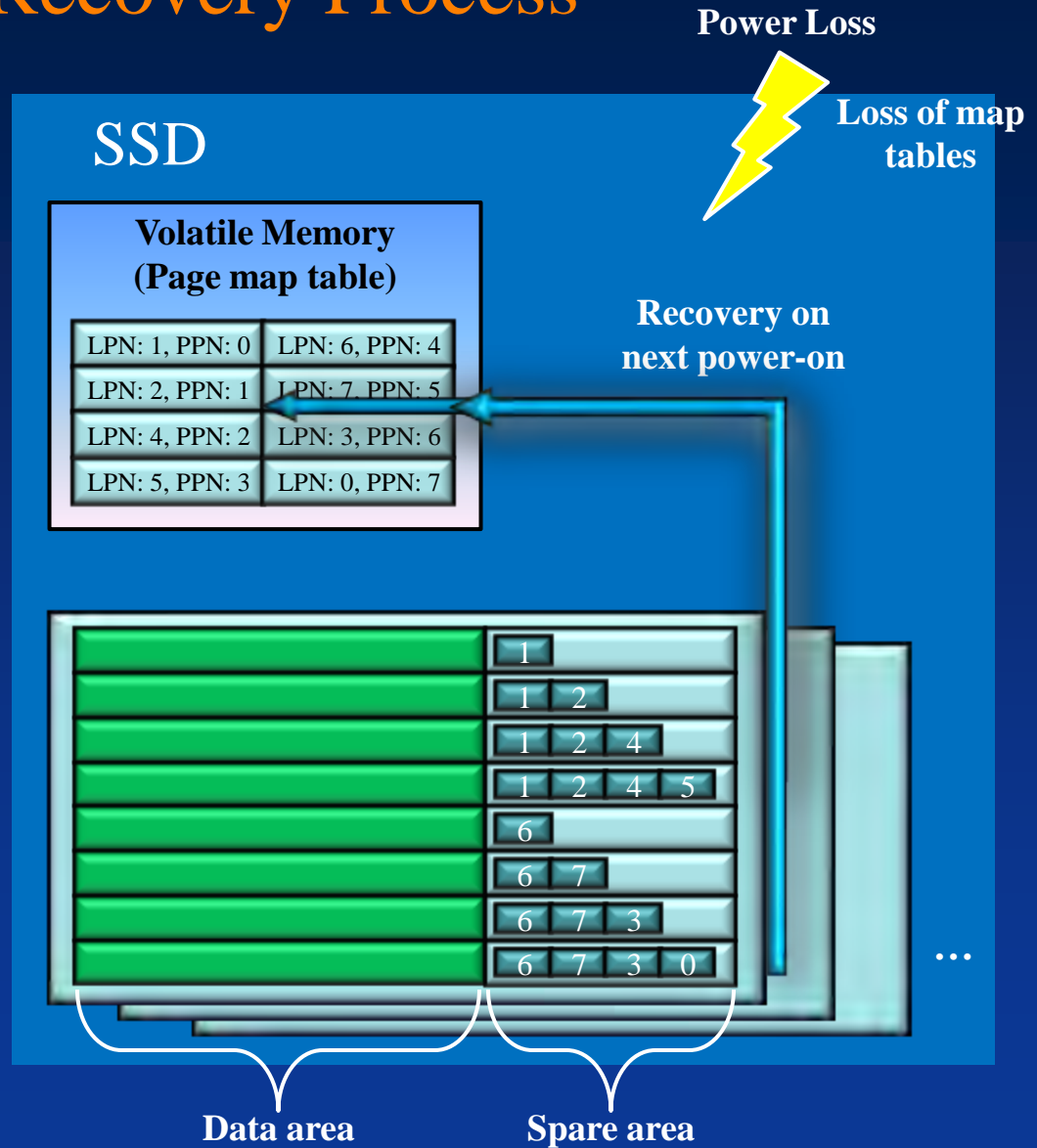
# PLR Schemes using Per-Page Spare Areas with No Synchronization Overhead

- Distribute Mapping Information over Spare Areas
- Different Approach according to Mapping Schemes
  - FTLs with page mapping
    - *Accumulation-based PLR (A-PLR)*
  - FTLs with hybrid mapping
    - *Signature-based PLR (S-PLR)*
- Tradeoff between Backup Cost and Recovery Latency

# A-PLR: Backup Process

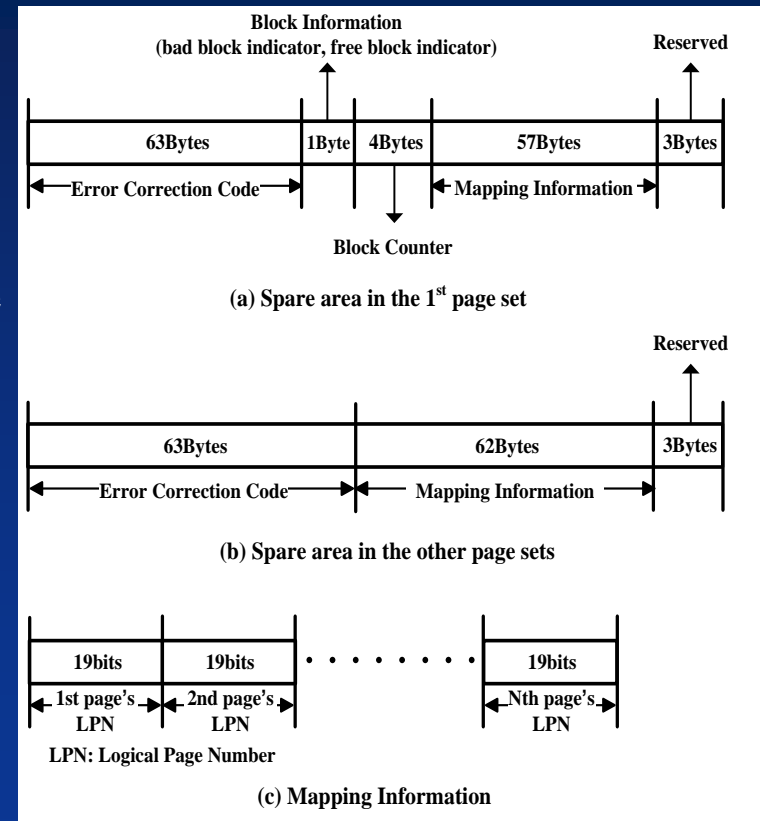


# A-PLR: Recovery Process

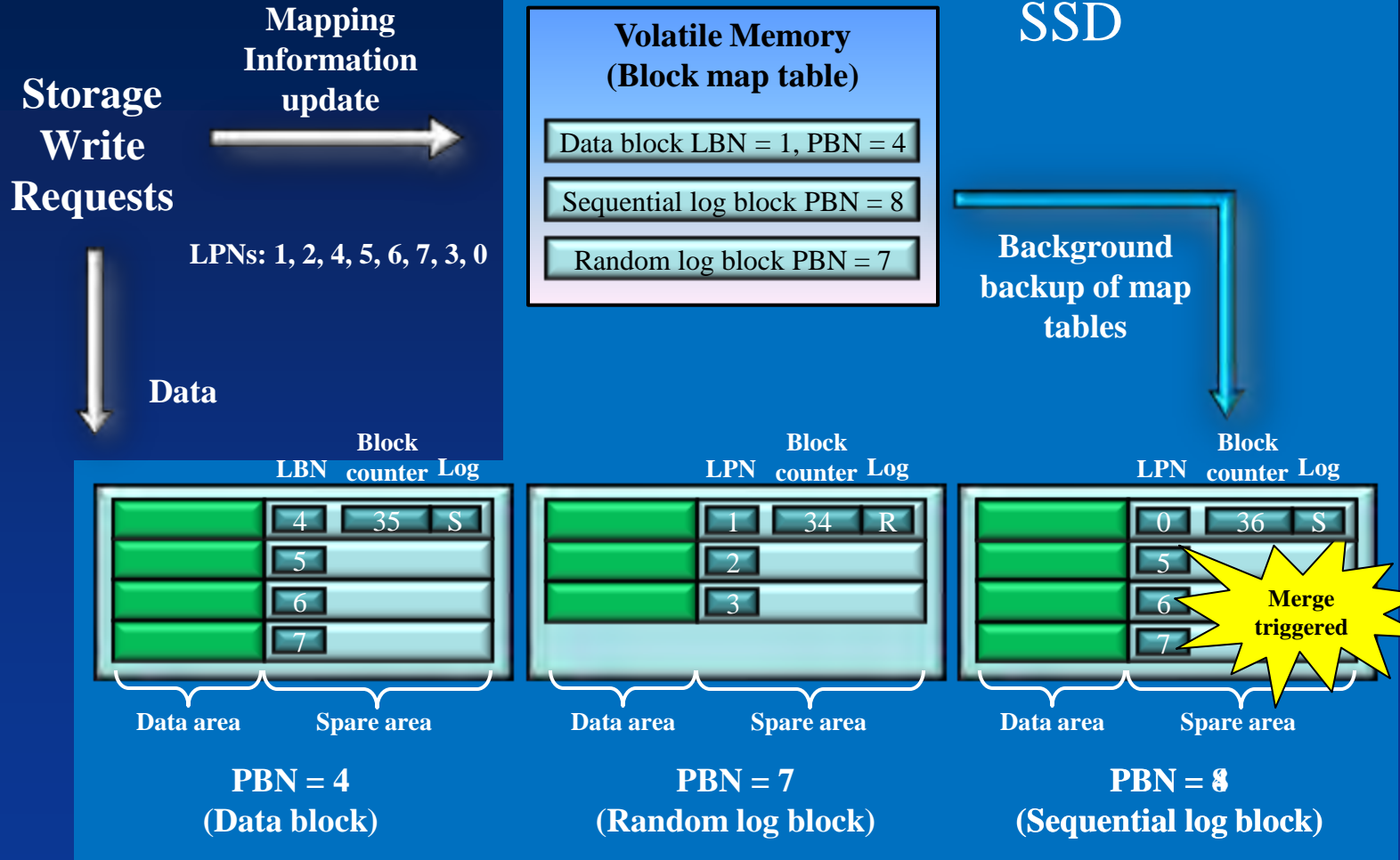


# A-PLR: Data Structure

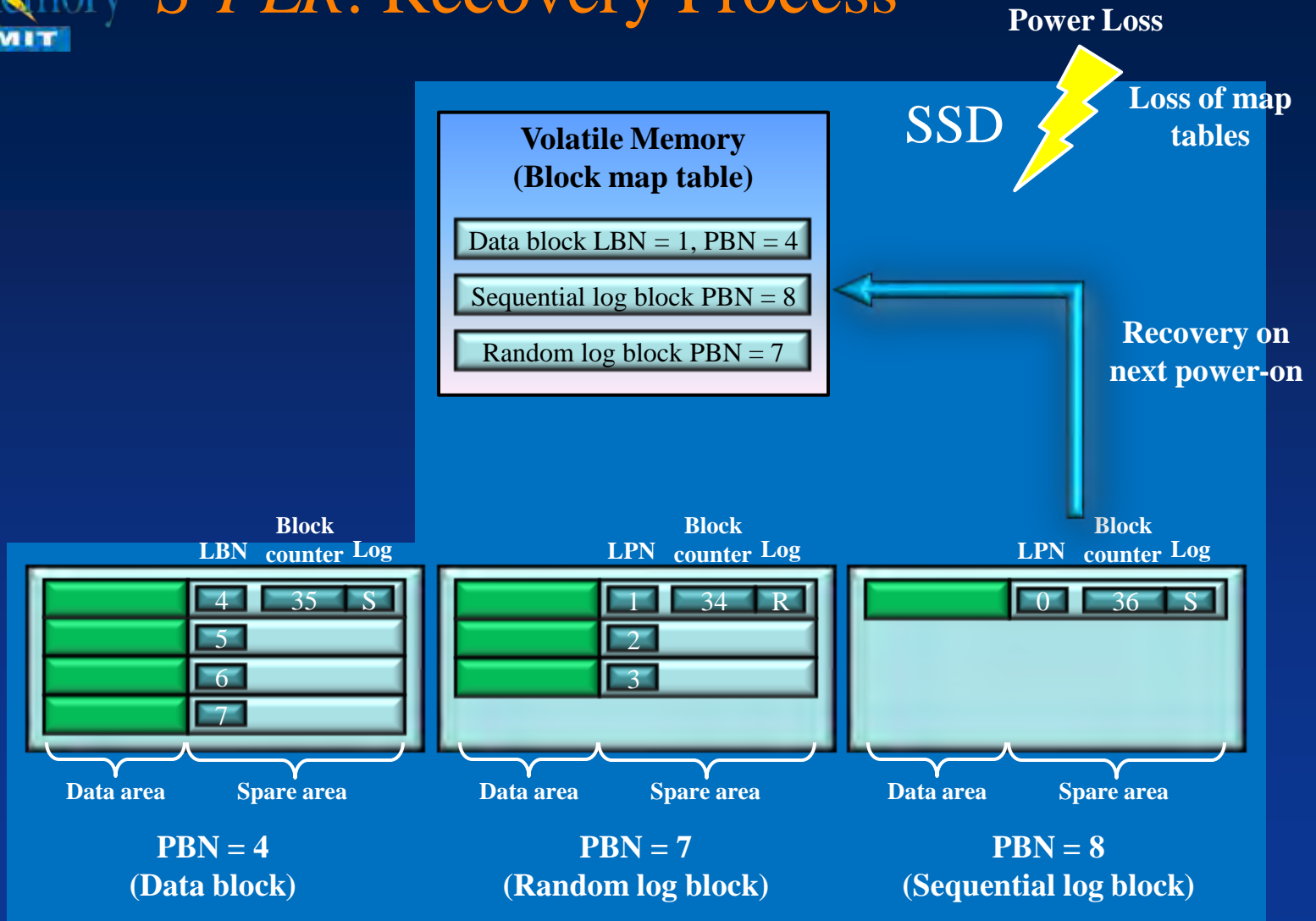
- Mapping Info Accumulation in Spare Areas
  - No additional overhead due to spare program in large block NAND flash
  - Power loss event before completing a new intermediate set
    - Searching with *b-tree algorithm* (log-scale search)
  
- Handling Duplicated LPNs
  - Storing block information and block counter in the first intermediate set
  - Power loss event during *GC and merge operations*
    - The same LPNs may be found in multiple blocks
    - Using the block counter as a recency indicator



# S-PLR: Backup Process

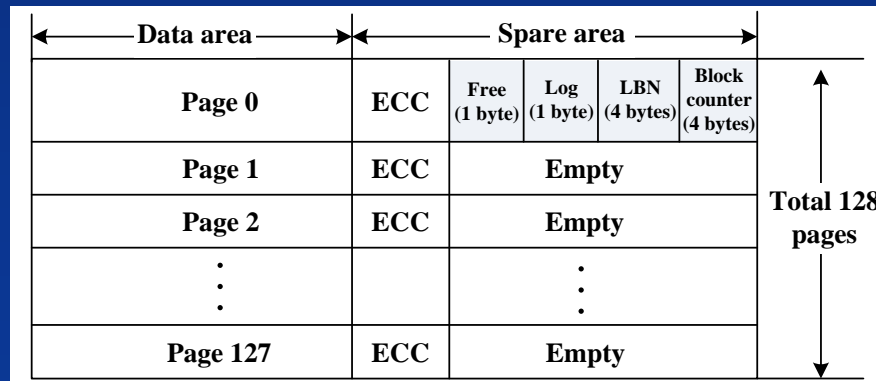


# S-PLR: Recovery Process

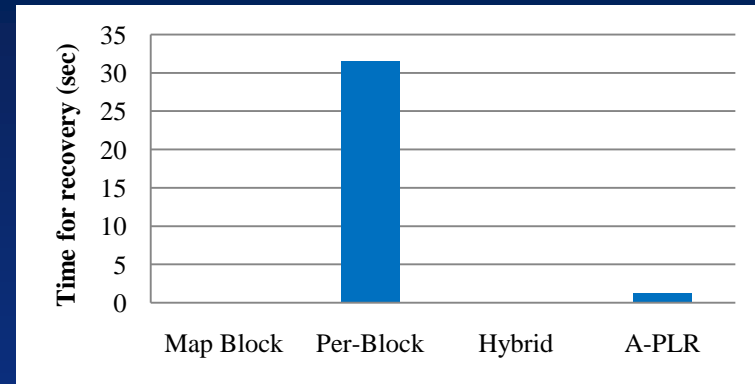
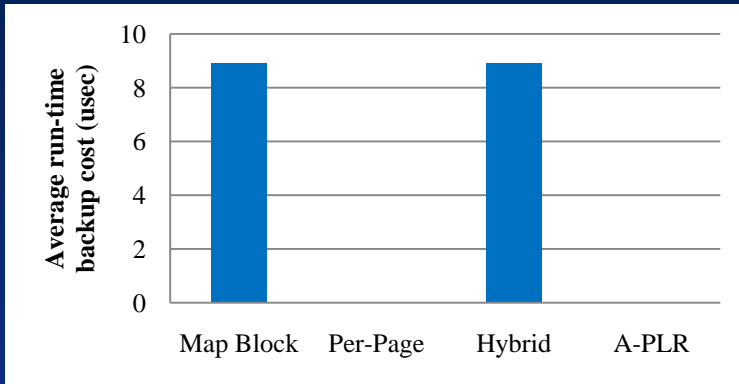


# S-PLR: Data Structure

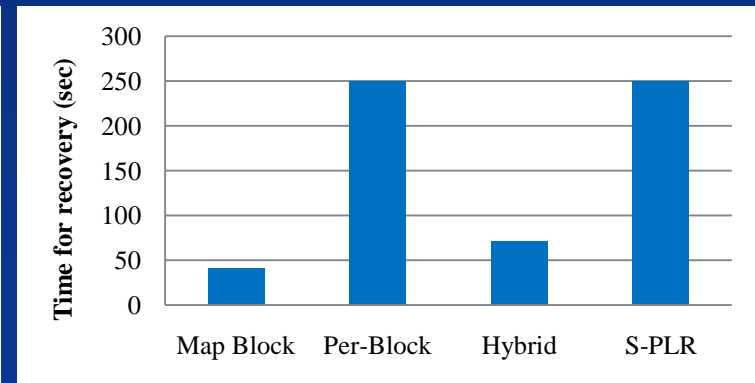
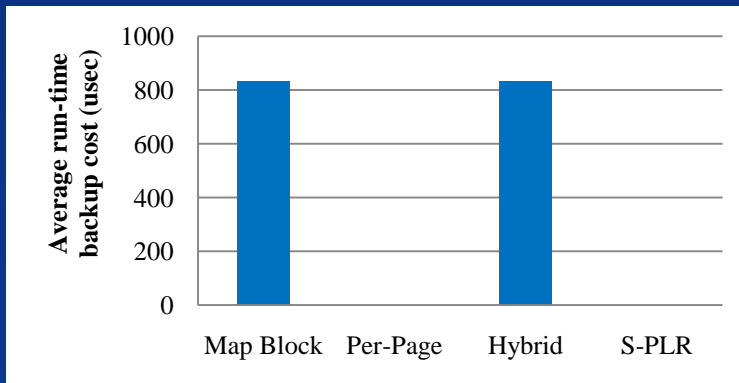
- Signature
  - *Free Flag*: whether the block is free or not
  - *Log Flag*: *S* (Sequential log), *R* (Random log), or *D* (Data block)
  - *LBN*: Logical Block Number
  - *Block Counter*: recency indicator
- Recovery Mechanism
  - Step 1: Reading the first pages of all blocks in NANDs
  - Step 2: Sorting blocks on *Log Flags* and then *Block Counters*
  - Step 3: Validating each block based on block use scenario



- *Page-Level Mapping (A-PLR)*



- *Block-Level Mapping (S-PLR)*





- PLR Schemes using Spare Areas
  - Efficient use of spare area
    - Mapping info accumulation (*A-PLR*) / signature (*S-PLR*) in spare areas in order to eliminate map blocks
  - Removal of space overhead and time latency
- Small Additional Delays for Multi-Chip SSDs
  - Recovery parallelism among channels and ways
- Future Work
  - PLR for FTLs with *data compression*



Thank you