

Flash Data Reduction Techniques and Expectations

.. or how to fit two tons of fertilizer in a one ton truck.

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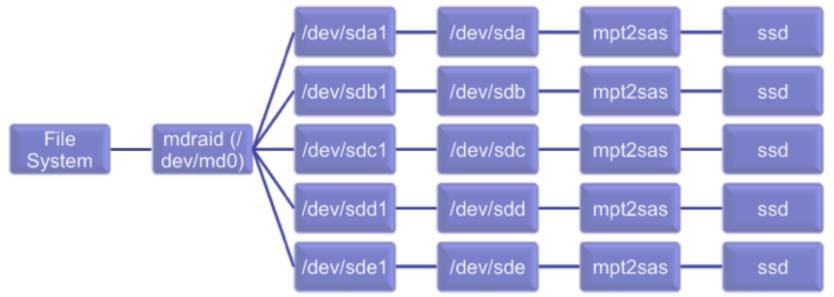




Most Block Devices have logic to handle Logical Block Addressing:

The RAW device starts at sector 0. Partition tables are simple offsets to the sector number.

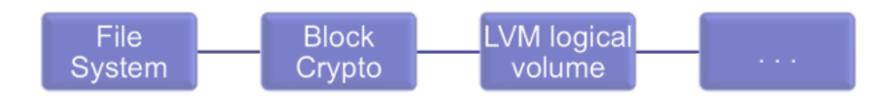
RAID mappings calculate where the block is stored across a collections of lower-level devices.





So far, the block stack has only dealt with "where" a block is stored.

Block stacks can also manipulate the contents of the blocks themselves.

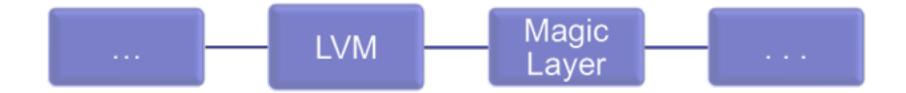




Now that we see how a block stack can re-arrange the location of blocks, and also manipulate the content of blocks, just how much trouble can we get into.

We have a few goals:

- •Optimize performance and wear for Flash
- •Optimize write behavior so that data is not lost or corrupted after a crash
- •Implement "thin provisioning"
- Implement "block-level compression"
- Implement "block-level de-duplication"





To keep Flash happy, we want to write to the media in controlled linear segments. If you dig inside of Flash SSDs, the Flash itself only understands linear updates. It is the SSDs FTL (Flash Translation Layer) that allows SSDs to support random writes at all.

Our external "Magic Layer" should off-load the FTL so that this function is performed globally and not local to a single SSD.

Here we accumulate a group of block updates, and place them into a linear write segment:

| Segment header | blk 1 Iba 89302 | blk 2 Iba 10472 | blk 3 Iba 9762 | blk 4 Iba 89103 | blk 5 Iba 21765 | | Segment footer | |
|-------------------|--------------------|--------------------|-------------------|--------------------|--------------------|--|-------------------|--|
|-------------------|--------------------|--------------------|-------------------|--------------------|--------------------|--|-------------------|--|

All of these blocks are the same size (4K). The header includes summary information, plus an array of the sector numbers associated with the blocks that follow.



The header (and footer if the write segment is long enough) has information about each block that follows.

The header can also include information about blocks that have no data. This allows you to write blocks that are empty (all zeros) or full (all FFFFs) without having the block actually occupy any space on the target device.

| Segment | blk 1 | blk 2 | blk 3 | blk 5 | blk 7 | blk 9 | Segment |
|---------|-----------|-----------|---------|-----------|-----------|----------|-------------|
| header | Iba 10765 | Iba 76302 | Iba 374 | Iba 10873 | Iba 76301 | Iba 2389 | footer |



Now that we can write linearly, compressing is pretty easy to manage.

If we compress each inbound 4K block, we can store at least some of these blocks in less than 4K bytes worth of space. Then this layout looks like:

| Segment header | blk 1 Iba 392 | blk 2 Iba 9382 blk 3 Iba 93 | blk 7 Iba 23 | blk 8 Iba 2 | blk 11 Iba 983 | blk 13 Iba 1045 | blk 15 Iba 221 | | Segment footer | |
|-------------------|------------------|--------------------------------------|-----------------|----------------|-------------------|--------------------|-------------------|--|-------------------|--|
|-------------------|------------------|--------------------------------------|-----------------|----------------|-------------------|--------------------|-------------------|--|-------------------|--|

With this layer, we have to track where a block is stored in more detail, but the write logic still maintains the advantages of 100% linear updates.



Now we de-dupe. With de-dupe, we look at the blocks contents and generate a unique ID using a function called a HASH.

With a unique ID, a write to a block that already exists is just like writing a zero or FFFF block.



The layer that remembers writes gets more complicated with de-dupe, but the write format remains the same.



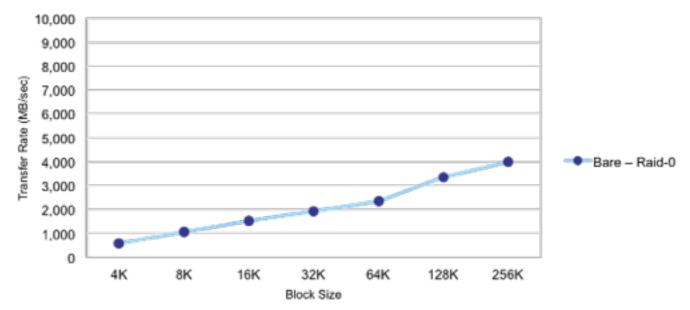
- Mapping requires some place to "remember" where blocks are stored
 - This can be a lot of memory
 - Thin provisioning, compression, and de-dupe put further demands on memory
 - Eventually, you have to store this data "on disk" which hurts performance.



- Compression takes CPU Cycles
- De-duplication HASH functions take CPU Cycles
 - De-duplication requires read validation to keep hash collisions from corrupting data.



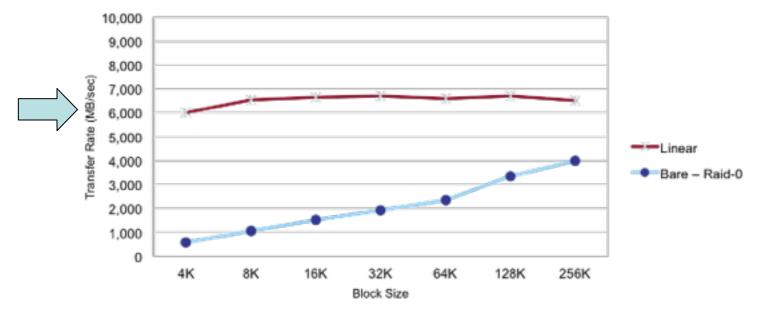
RAID-0 Base Line Performance



10 Thread Random Write Performance



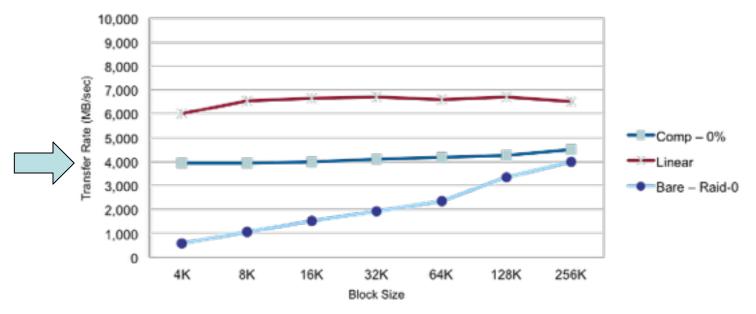
• RAID-0 Linear Writing



10 Thread Random Write Performance



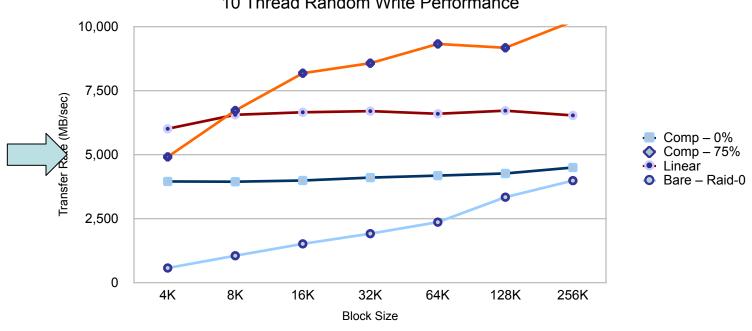
• RAID-0 Linear Writing w/ Compression uncompressible data



10 Thread Random Write Performance



 RAID-0 Linear Writing w/ Compression 75% compressible data

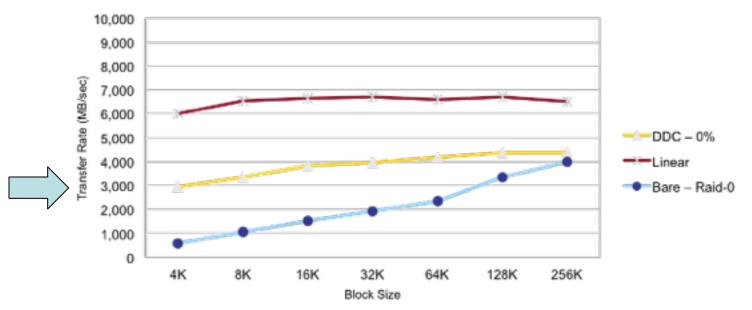


10 Thread Random Write Performance



Linear Writing w/ Compress and De-dupe

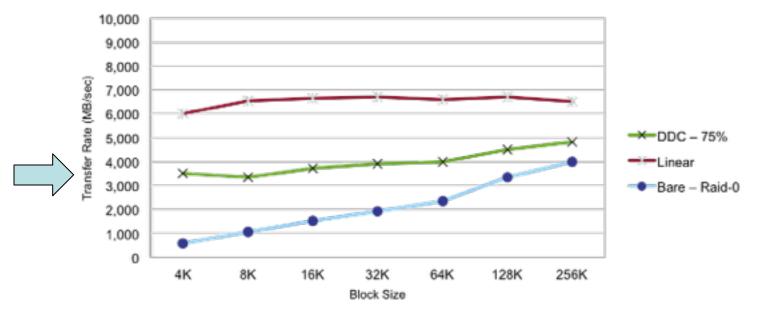
uncompressible data



10 Thread Random Write Performance



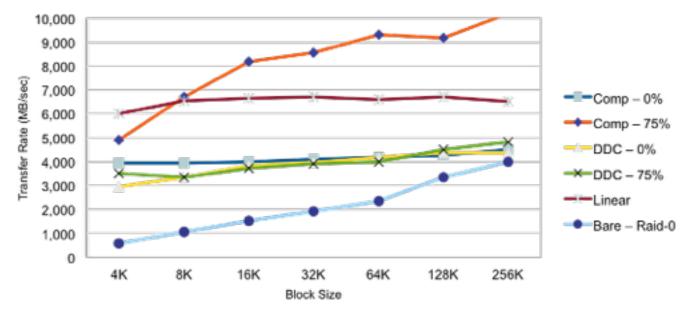
• Linear Writing w/ Compress and De-dupe 75% compressible data



10 Thread Random Write Performance



RAID-0 Tests Compared

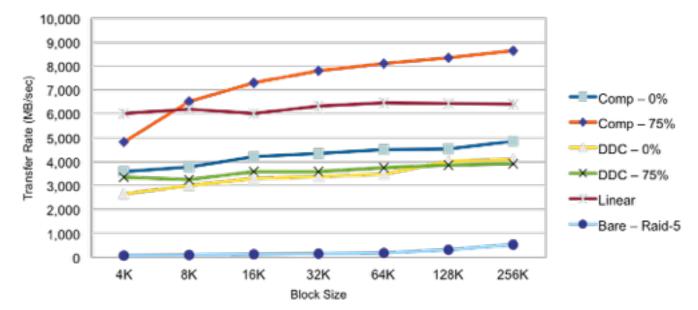


10 Thread Random Write Performance



RAID-5 Tests

destroys native performance, but leaves linear writing intact.



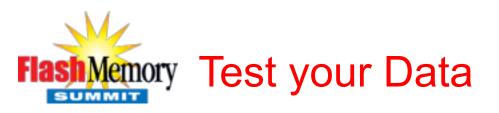
10 Thread Random Write Performance



- Block Layer Software can give you
 - Superior write performance
 - Superior flash wear
 - Improved crash data protection
 - Thin provisioning
 - In-line compression
 - In-line de-duplication



- Not all datasets compress
- Not all datasets have duplicate blocks
- Best applications
 - Virtual server farms
 - VDI
 - Databases
- Worst applications
 - Media and Entertainment
 - Encrypted / compressed files



- EasyCo has a simple, read-only tool that will scan block volumes and report compressibility and de-dupe potential.
 - Can be run on a single volume
 - Can be run on multiple volumes, even on different systems, and the results consolidated.
- http://easyco.com/dedupe-calc.htm



- Data reduction can lower storage costs while still maintaining excellent performance:
 - Drives pure flash storage costs below \$0.20/GB
 - Keep symmetric read/write IOPS above 500K