

### **Erasure Coding for Flash Devices and Systems**

### Flash Memory Summit 2015 PreConference Seminar A

Steven Hetzler IBM Fellow Manager, Cloud Data Architecture

Flash Memory Summit 2015

Steven Hetzler, IBM

### Outline

• Discussion of uncorrectable bit errors (UBER)

• Basic erasure coding and non-recoverable read errors

• System failure targets

• PMDS codes

• Fun and games with erasure codes

### **UBER: Uncorrectable Bit Errors**

The "other" component of reliability

- UBER is when there are more bit errors than the sector ECC can correct
  - For example, if the sector ECC can correct 50 bits, but there are more than 50 bits in error
- One component of non-recoverable read errors (NRRE)
  - 2 outcomes of an NRRE event:
    - The ECC detects the error count is too large, and declares the sector lost
    - The ECC blissfully applies the correction and produces an incorrect value (miscorrection)
      - This can be messy, as the number of errors will be > 2 x correction\_bits + 1
      - It's common to add CRC to catch such events and convert to NRRE events
- I'll use the term NRRE going forward in this analysis

#### NRRE events

- NRRE events are contributors to data loss
  - Impact depends on the system architecture
  - Loss is at least a sector worth of bits
- NRRE is specified as an interval: e.g. < 1 in  $10^{14}$  bits
- Or as a rate: e.g. <=10<sup>-14</sup> per bit
- 10<sup>14</sup> bits seems really large
  - But there are  $0.08 \times 10^{14}$  bits in a terabyte!

# **NRRE Specifications**

Alternative expressions which are easier to use

- Express as rate per TB transferred
  - Nice for computing from data moved
  - NRRE/TB = error\_interval/8 x  $10^{12}$
- Express as sector failure probability per operation (sector read)
  - More accurate, since we lose a sector on an NRRE event, not a bit
  - psfail = sector\_bits/error\_interval

### **Alternate NRRE Specifications**

Some typical specifications (assume 1kB sectors)

- Examples of interval specifications and their equivalents
- Both the probability per TB and the probability of failure are easier to use for system reliability

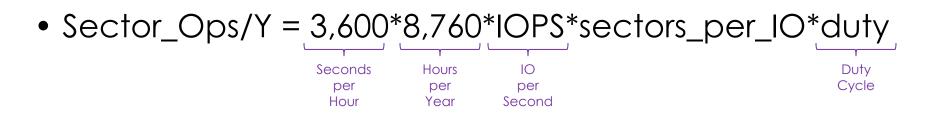
	Consumer HDD	Enterprise SSD
Typical NRRE Spec (b)	1e14	1e17
NRRE/TB	8%	8e-5
psfail	8.2e-11	8.2e-14

#### **NRRE Specs and Data Loss**

#### Simple to estimate

psfail = sector\_bits/error\_interval

- Assuming error-interval is >> 1



- Mean Y/Sector Loss = 1/(Sector\_Ops/Y \* psfail)
- Duty cycle effects are small here
  - R/W typically 70/30, but depends on application
  - Active duty cycle: ~80% enterprise, ~20% consumer

# **Probability of NRRE per Year**

We can work out annual reliability using prior equations

• Consider a consumer SSD and an enterprise SSD

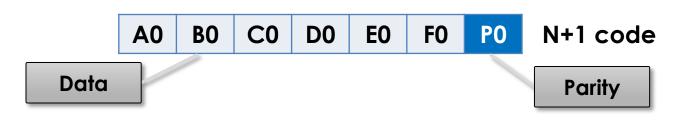
Device	Consumer SSD	Enterprise SSD
IOPS (4kB)	20,000	200,000
Sector Ops/Y (@duty)	1.3e11	5.1e12
NRRE interval (bits)	1e16	1e17
psfail	8.2e-13	8.2e-14
Mean Y/Sector Loss	2.4	0.6
Sector Loss/Y EV	0.4	1.7
MTTDL (MHours)	0.02	0.005
Drive MTBF (MHours)	2	2

- Rate of occurrence is high relative to 2MH drive MTBF
  - Good idea to use an erasure code to protect against NRRE
  - Oh, and device failure as well..

# **Erasure Correcting Codes**

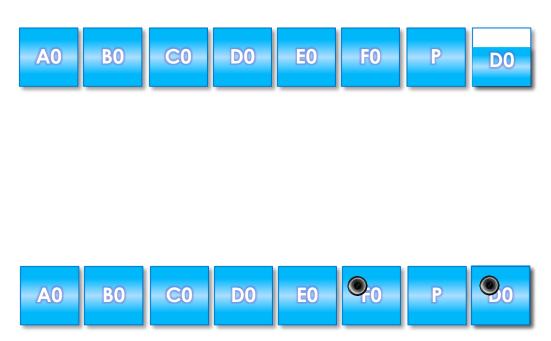
#### Protecting against device loss and sector loss

- Erasure correcting codes protect against unit loss
  - Can be hardware or software based
  - Unit can be a sector, a chip, a drive, ...
- Terminology
  - Parity unit
    - A unit containing erasure code information
  - Erasure
    - An error whose location we know
    - Such as a unit that has failed



## Data Loss Types

- Array Loss
  - Lose a 1<sup>st</sup> unit
  - Start rebuild onto spare
  - Lose 2<sup>nd</sup> unit during rebuild
  - Large data loss
- NRRE Loss
  - Lose a first unit
  - Hit an NRRE on rebuild
  - Small data loss
- Example here is for N+1 code



### Should We Worry About NRRE?

Sometimes, we need to read the entire drive

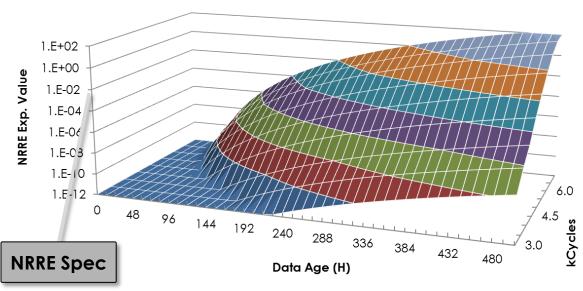
- We can compute the expectation value for hitting an NRRE during a drive read (DR) operation
- ev\_NRRE\_DR = psfail\*sectors\_per\_drive
  - (If << 1, then same as probability)
  - Assuming NRRE are not correlated (which isn't true for flash...)

Device	Consumer SSD	Enterprise SSD	
Sector kBytes	1	1	
Drive TB	1	1	
Sectors/drive	1e9	1e9	
NRRE interval (bits)	1e16	1e17	
psfail	8.2e-13	8.2e-14	
ev NRRE/DR	8e-4	8e-5	

# **NRRE on Rebuild**

- An issue for rebuilds with no further protection
- On rebuild, we need to read all the remaining data
- Will have a distribution of cycle count/data ages
- Data shown for SSD with 1e15 NRRE interval spec (=4.3e-12)
- This 1TB SSD has 2e9 sectors, so @ spec, NRRE ev is 9e-3!
- Much of the surface is out of spec
- Spec isn't very good to begin with
- An array has multiple devices
- EV will be multiplied by # drives read
- w/8 drives, spec prob NRRE is 7%!
- NRRE are correlated by common cycle count and data age in an erase block

Device data on expectation value when reading device capacity on a 1TB SSD



**Expectation Value for NRRE in Full Drive Read** 

Flash Memory Summit 2015

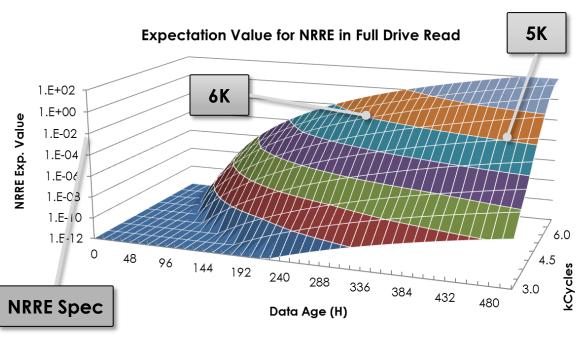
Steven Hetzler, IBM

# **Cost of Protecting Against NRRE**

- NRRE impacts reliability during rebuilds
- If units are lost, we need to rebuild the missing data
- The code will determine how many failures can be tolerated
- If there is no parity left, a sector loss becomes a data loss event
- Scrubbing can sometimes help
- But adds to cycle pressure
- If we know the surface, we can pick a maximum data age for scrubbing

kCyc	Age(H)
3	1,500
4	850
5	460
6	280

Device data on expectation value when reading device capacity on a 1TB SSD



Flash Memory Summit 2015

Steven Hetzler, IBM

# NRRE and Erasure Correcting Codes

#### Protecting against device loss and sector loss

- There are erasure codes which protect against both device loss and NRRE
  - While scrubbing can help, it's not enough by itself
  - Reducing the rebuild time window won't help much
    - NRRE expectation value largely independent of rebuild time
- Probability of data loss depends on the erasure code properties and the device properties
- Codes can be designed which can efficiently protect against these events
- First, determine how much protection is needed

# **Failure Targets**

#### How to create data loss targets for a system

- Failure events should be expressed per unit time
  - This is how the customer experiences events
    - Not per byte, or per IO
- Program based targets
  - Look at the behavior of an entire field population
    - Helps for modeling warranty costs
    - Also helps with program financial targets

# **Program Failure Targets**

Inputs to program based tarets

- Install base
  - Unit ships per year, field lifetime, program lifetime
- Usage characteristics
  - Total data operations, total data transferred
- Failure tolerance
  - Depends on the failure type
  - Is it a warranty event, loss of availability, loss of data or customer near-death experience?

# **Modeling Failures**

(Precision is highly over rated here...)

- We need only compute first order terms!
- Why?
- Assumptions are errors are independent of each other and of time
  - These are rarely true
    - (Well, essentially not at all with Flash...)
- The biggest deviations will be from these assumptions
- So first order is good enough
  - Still a good idea to verify which terms are second order
- Thus, we can compute from binomials
  - Easy to do in a spreadsheet too!

#### System Data Loss Targets

Program Design	Value	Notes
Field lifetime (Y	5	Typical
Mean field units	250,000	Assume a successful program
Units/Array	8	Erasure code span
IO size (kB)	4	Assume transaction processing
Total field IOs	2e18	Assume 50,000 IOPS/unit
Arrays/field	31,250	

Program Loss Targets	Value	Notes
Data Loss Events/program	1	For the entire program
Target Prob data loss/array/Y	2e-6	Assume a successful program

### System Data Loss Targets - Device

The system is built from these devices

- Here is an example device we might encounter
  - Recall ev\_NRRE\_DR = psfail\*sectors\_per\_drive

Item	Value	Item	Value	Item	Value
IOPS	50,000	Capacity (TB)	1	Sector kB	1
AFR	0.5%	NRRE	1e16	Sectors	1e9
ev NRRE DR	8.8e-4	Rebuild (H)	2.8		

# **Computing Sector Failure Targets**

psfail that meets the system target

- psfail1f is the sector failure rate with 1 unit failure
   We have a 1TB SSD and1kB sectors here
- psfail1f needed to meet array data loss target with 1 unit failure
  - psfail1f = TgtDataLoss/Y / (sectorsread\*P1fail/Y)

- psfail1f = 4.55e-15
- (NRRE1f = 4.87E-19 is the equivalent NRRE to psfail1f)

# **Cumulative Binomial**

Useful for estimating failures

- cumbinomial(fails,trials,errorrate)
  - Fails is the number of failures
  - Trials is the total number of events (ops, bits, etc.)
  - errorrate is the failure rate per trial (e.g. ber, AFR)
- This is the cumulative binomial distribution
   In Excel, use the Binom.Dist function as:
  - 1-Binom.Dist(fails,trials,errorrate,TRUE)
  - Be aware sometimes this runs out of precision when it shouldn't
  - Then it just reports 0 happens around 1e-15, which isn't that small

# Array Down 1 Unit

Probability an array has lost 1 unit in a year

- P1fail is the probability there is one failure in an array
- Probability an array is down 1 unit:
  - P1fail/Y = 1-binomial(0,arraysize,AFR) = 3.9% here
  - Not surprising:
    - 0.5% AFR \* 8 units ~= 4%
    - 0.5% AFR = 1.75MH MTBF
  - Large MTBFs like 2MH don't mean things are super reliable
    - AFR = 8760/MTBF
    - So, at 2MH MTBF, annual failure rate is 0.44%
    - That is, for every 100 drives, there is a 44% chance of 1 of them failing in a year

# Did you Notice?

Our device is out of spec for the system

- Recall our SSD had NRRE 1e16
- Which has psfail = 8.8e-13
- But we need psfail = 4.55e-15!
- So, this device doesn't work here as specified
   And a drive at 1e-17 won't quite work either
  - Just a little hint of what's to come

# Reliability for N+1 Array

Single parity per array: 87.5% efficient on 8 units

- There are 2 terms array loss and NRRE loss
  - Both start at prob 1 unit is lost
  - Array loss
    - And 2<sup>nd</sup> unit lost during rebuild interval (RH is rebuild time in hours)
    - P2Fail/R = 1-binomial(0,arraysize-1,AFR\*RH/8760)
       = 1.1e-5
  - NRRE loss
    - And NRRE occurs during rebuild
    - PNRRE/R = ev\_NRRE\_DR \* (arraysize-1) (if ec\_NRRE\_DR << 1) = 5.6e-3
- PFail/Y = P1Fail/Y $\sqrt{(PNRRE/R)^2 + (P2Fail/R)^2}$ = 2.2e-4
  - Oops 100x out of spec (which is 2e-6)
    - Prob array loss only is 2e-7, so this would be OK

# Reliability for N+2 Array

Two parities per array: 75% efficient on 8 units

- Again, there are 2 terms array loss and NRRE loss
  - Both start at prob 1 unit is lost \* prob 2<sup>nd</sup> fail in rebuild
    - P2Fail/Y = P1Fail/Y\* (1-binomial(0,arraysize-2,AFR\*RH/8760))/2 = 2.2e-7
  - Array loss
    - And 3<sup>nd</sup> unit lost during rebuild interval (RH is rebuild time in hours)
    - P3Fail/R = 1-binomial(0,arraysize-2,AFR\*RH/8760) = 9.7e-6
  - NRRE loss
    - And NRRE occurs during rebuild (if ec\_NRRE\_DR << 1)
    - PNRRE/R = ev\_NRRE\_DR \* (arraysize-2) = 4.8e-3
- PFail/Y = P2Fail/Y $\sqrt{(PNRRE/R)^2 + (P3Fail/R)^2}$ = 1.1e-9
  - Much better than spec, which is 2e-6

### Results

#### So, we are done then?

- N+1 didn't meet the data loss target, but N+2 did
- Note that N+2 operates at 75% data efficiency
  - Uses an entire unit's worth of data to protect against an NRRE
  - This is wasteful
  - You can see it in the terms
    - P3Fail/R = 9.7e-6
    - ev\_NRRE\_DR = 4.8e-3
  - NRRE term dominates during rebuild
- What we need is an erasure code that separates NRRE protection from unit protection
  - Don't use a hammer to kill a fly (fun though it may be)
- New term: fpof first point of failure
  - The minimum number of losses that cause a failure

### **PMDS** Codes

#### Optimized for both device and sector protection

- New erasure codes designed for this very problem
  - (I know, I was there when it happened)
  - Parity group is now multiple sectors from each device (columns)

<b>A</b> 0	BO	C0	D0	EO	PO
A1	B1	C1	D1	E1	<b>P1</b>
A2	B2	C2	D2	E2	<b>P2</b>
A3	<b>B3</b>	C3	D3	E3	<b>P3</b>
A4	<b>B4</b>	C4	q <sub>a</sub>	q <sub>b</sub>	<b>P4</b>

P0 is row 0 parity (Example with 6 units)
P1 is row 1 parity
P2 is row 2 parity
P3 is row 3 parity
P4 is row 4 parity, q<sub>a</sub>, q<sub>b</sub> group parities

- Unit loss protection via row parities P<sub>n</sub>
- Floating sector loss protection via group parities q<sub>n</sub>
  - The  $q_n$  can be placed anywhere in the parity group
  - Invoked only after more than 1 sector in a row is lost
  - This code is called PMDS 1+2 (1 unit + 2 group)

# What Are PMDS Codes

#### Partial Maximum Distance Separable Codes

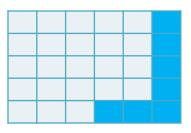
- An extension of MDS codes
- MDS codes can correct as many erasures as they have parities
  - N+1 and N+2 are MDS codes
- PMDS codes are partially MDS in efficiency
  - They have more parities per correction than MDS codes
  - But they can approach the MDS in efficiency
- We classify them as n+m
  - Where n is the number of full parity columns
  - m is the number of group parities
    - The group parities can correct errors anywhere in the goup
  - If the number of rows is large, the efficiency can ~MDS

Blaum, Hafner, Hetzler: "Partial-MDS Codes and Their Application to RAID Type of Architectures", IEEE Transactions on Information Theory 59(7): 4510-4519 (2013).

# **PMDS Code Correction**

#### Why PMDS codes are so handy

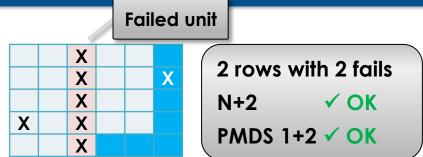
• Consider the PMDS 1+2 code below (6 units)

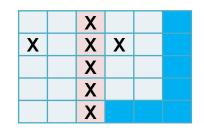


- It has a minimum Hamming distance of 4 to sector loss
  - That is, it can correct any 3 such failures (4 in a row fail)
- It can correct many patterns of 4 failures
  - Such as 2 rows with 2
  - Or 2 columns with 2 (important after a column failure)
  - These are important for flash as sector failures can correlate in both rows and columns

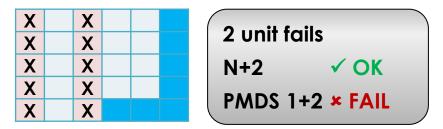
## PMDS 1+2

- PMDS 1+2 in most cases is stronger than N+2
  - Consider rebuild (1 unit fail)
  - N+2:
    - Correct all 1 sector fail/row
    - Correct 0 2 sector fail/row
    - Fpof = 2 sectors + 1 unit
  - PMDS 1+2:
    - Correct 2 1 sector fail/row
    - Correct 1 2 sector fail/row
    - Fpof = 3 sectors + 1 unit
  - For independent failures, first order is # of failures









- PMDS 1+2 is stronger to sector failure on rebuild
- PMDS 1+2 is weaker to unit fails
  - Mitigated by short rebuild time

# PMDS 1+2 Reliability

#### PMDS 1+2 with 32 rows: 87% efficiency on 8 units

- There are 2 terms array loss and NRRE loss
  - Both start at prob 1 unit is lost
  - Array loss same as N+1: P2Fail/R = 1.1e-5
  - NRRE loss
    - Prob of 3 NRREs in the remaining sectors in the group
    - PGFail/R = cumbinomial(3,32x7,psfail) = 1.2e-30
    - Prob rebuild fails = cumbinomial(1,ngroups,PGFail/R) = 3.4e-23
- $PFail/Y = P1Fail/Y\sqrt{(PNRRE/R)^2 + (P2Fail/R)^2}$ = 2.2e-7
  - Which exceeds the spec of 2e-6
- PMDS is almost as efficient as N+1, but 1,000x more reliable

Flash Memory Summit 2015

### **General PMDS Codes**

PMDS codes can be highly customized

- PMDS n+m codes can be created for various configurations of n and m
- Examples:
  - PMDS 1+1 reduced sector loss coverage compared to 1+2
  - PMDS 2+1 N+2 with single sector loss coverage
  - PMDS 2+2 N+2 with double sector loss coverage
- I like to have at least n+2 to give some coverage for correlated NRRE events
  - Flash has a high degree of correlation
    - All drives in array have almost identical cycle counts and data ages
- While the example here was a cross-drive array, the analysis holds for intra-drive arrays (across dies)

#### Some Games We Can Play

We extract more value from the sector protection of PMDS 1+2

- We can allow the unit NRRE to be much greater than the specification, and let the PMDS code reconstruct the data
- We can do this by reducing the power of the in unit sector ECC, improving the overall data efficiency
- I call this DNR ECC ("Do Not Resuscitate")
  - The unit should not try so hard to recover from sector errors

# **DNR ECC**

#### We let sectors fail at a higher rate with DNR ECC

• Failure (at the flash layer) is acceptable with a proper erasure code at the array level

- With larger limits than solo devices permit

- System can be optimized by adjusting the correction at each level
- No need to try so hard at the flash layer
  - DNR we deliberately set a higher failure rate target at the component level
  - Improves flash efficiency, simplifies encode/decode
    - Need to correct fewer errors
    - Makes the components more testable
      - Lowered expectations being more common these days...

# Aside on Computing NRRE Targets

How to get the raw bit error rate from the NRRE and the sector ECC

- We can compute the raw ber from the psfail spec and ECC if we know the sector ECC
  - psfail target was 4.6e-15
  - 1. Assume BCH 66 code on 1kB
    - Corrects 66 bit errors out of 1,024 data bytes
    - Requires 924 check bits
    - sectorbits = databits + checkbits + metadata ~ 9,212
  - 2. psfail = (1 cumbinomial(66,sectorbits,ber))/sectorbits
  - 3. Invert by iteration to solve for ber
  - 4. Here: ber = 2.65e-3
  - 5. To meet system target need @ ber 2.65e-3 need 75 bits
    - 9,338 sectorbits
    - Hint: you can use Goal Seek in Excel to quickly iterate to find the ber

#### Our SSD

Need some further information

- Let's assume our SSD has an internal ECC
- Corrects up to 66 bits in error
- The sector has a total overhead of 924 bits
- So the sector size is 9,212b (8,192b are user data)
- Data efficiency is thus 89%
- Now, we can compute the required psfail to reach our array target
  - And thus the ECC correction bits required

Flash Memory Summit 2015

#### DNR Results for N+1 and N+2

Code Type	N+1	N+2
sparity/pgroup	0	1
sectors/pgroup	10	10
pgroup/array	1e9	1e9
Code data efficiency	0.90	0.80

Failure computations		
parrayfail	2.0e-6	2.0e-6
psfail	4.6e-15	3.4e-8
ECC corr bits needed	75	55
Sector efficiency	0.88	0.90

#### Not the answer the judges were looking for!

Net data efficiency

Steven Hetzler, IBM

0.79

0.72

### PMDS DNR Results

Code Type	N+1	N+2	PMDS 1+1	PMDS 1+2
sparity/pgroup	0	1	1	2
sectors/pgroup	10	10	160	1,280
pgroup/Array	1e9	1e9	6.3e7	7.8e6
Code data efficiency	0.90	0.80	0.89	0.90

Failure computatio	าร				
parrayfail		2.0e-6	2.0e-6	2.0e-6	2.0e-6
psfail	4.6e-15		3.4e-8	7.2e-9	2.5e-7
ECC corr bits		75	55	56	52
Sector efficiency		0.88	0.90	0.90	0.91
	We have a winner				
Net data efficiency		0.79	0.72	0.81	0.82

# **DNR Results with PMDS Codes**

#### PMDS 1+2 makes DNR ECC cost effective

- Efficiency is increased by letting the NRRE (psfail) increase
  - Up to 3% more efficient in this example
- May not sound like much, but worthwhile
  - Goes straight to margin
    - What else would you do for 3 margin points?
  - Can also be used to increase yields
  - May save cost in ECC decoders
  - Can allow use of consumer parts in enterprise applications
- This was just a simple example, we may be able to do better with other configurations
- If you need dual unit failure protection, there are PMDS codes for those as well
  - If 2<sup>nd</sup> parity is protecting against a second unit failure, it's not available for sector loss protection
    - I have shown you how to do the math

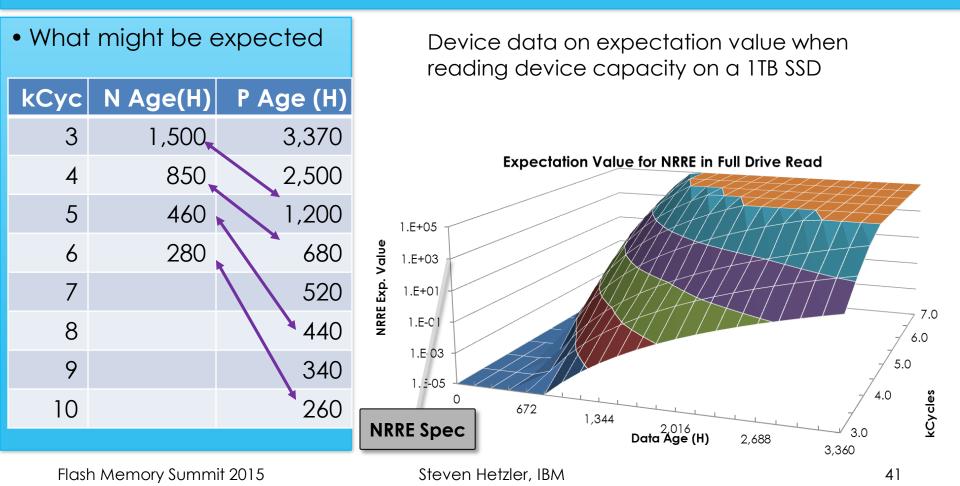
# PMDS 1+2 DNR ECC

If we can't change the ECC, we can push the device

- Target data loss per year is 2e-6
- Our example has 3.9% AFR, P2Fail/R = 1.1e-5
- Recall PMDS 1+2 had PNRRE/R = 3.4e-23
- So we can tolerate much higher NRRE
- $PFail/Y = P1Fail/Y\sqrt{(PNRRE/R)^2 + (P2Fail/R)^2}$
- So our target is PNRRE/R = 2e-6 (17 orders higher!)
  - PNRRE/R = cumbinomial(1,ngroups,PGFail/R) = 5e-5
  - PGFail/R = cumbinomial(3,32x7,psfail) = 1.6e-12 (invert)
  - psfail = 9.5e-7
  - This is 1e6 x the psfail = 8.8e-13 for 1e16 devices

#### PMDS 1+2 DNR Results

- We have psfail = 9.5e-7
- On the 1TB drive, this gives ev NRRE/DR = 9.5e2 (Yes Virginia, it loses data!)
- This will give us relief in cycle count or data age (our choice)
- Nice gains for adding NRRE protection



# **Operational Gains From PDMS 1+2**

There are advantages to allowing failures

• Endurance gains at constant retention

kCycles	3	4	4	6	7
Retention Gains	2.3	2.9	2.7	2.4	2.5

• Retention gains at constant endurance

Retention (H)	1,500	850	450	300	200
Cycle Gains	1.6	1.4	1.6	1.6	1.8

- The gains here are substantial
- However, reality can intrude

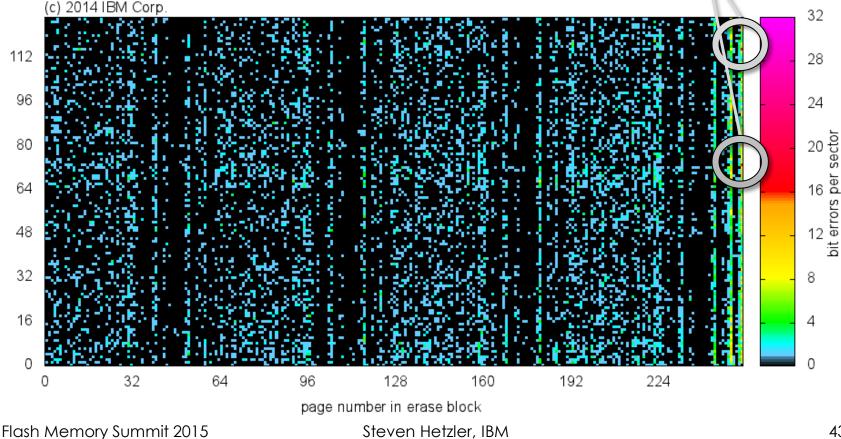
Flash Memory Summit 2015

#### **Actual SSD Data on Error Behavior**

- Sector error count bitmap from an SSD
  - Bit errors have a significant tendency to cluster
  - So of course, do the NRREs
  - "If you see red, the sector is dead" (NRRE)



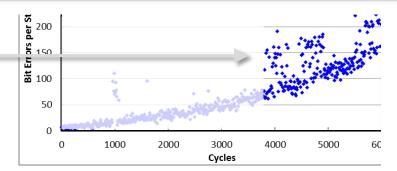
4A0000 61C PE: 3000; age: 276.41 H; max: 17; mean 0.31; fails 2



43

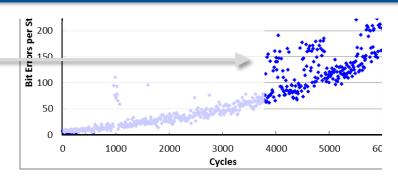
# **Error Clustering in Space and Time**

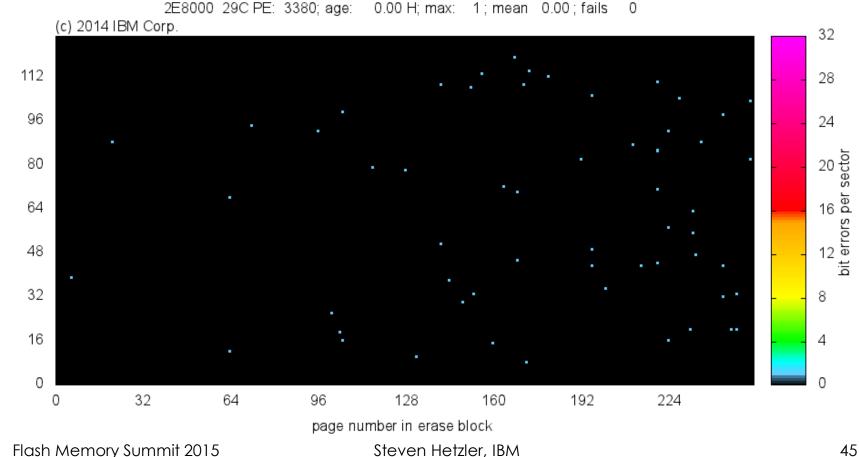
Let's look at PE 4,000 – 6,000
– Watch the evolution



# **Error Clustering in Space and Time**

- Let's look at PE 4,000 6,000 - Watch the evolution
  - Did you see the double?





Flash Memory Summit 2015

sector number in stripe

# Effects of Errors Being Non-random

- The net effect is that the reliability calculations we have performed will be too optimistic
- This means we should leave some headroom in the targets
- Increases the need for stronger erasure codes
- Increases the value of codes like PMDS
  - Don't want to pay a large penalty for the average sector, when outliers are the problem
  - Adding NRRE protection like PMDS efficiently targets the issue
  - The relative gains might be greater than shown here
  - However, need data on error behavior to confirm

### Summary

- I have shown the importance of handling NRRE events
- I have shown how to set reliability targets for flash systems
- I have shown how to compute reliability for systems using various erasure codes
- PMDS codes are more efficient than classic N+M parity
   PMDS codes are designed to protect against both unit loss and NRRE events
- DNR ECC can be combined with PMDS to codes for even greater efficiency