

## High Performance FTL for PCIe/NVMe SSDs

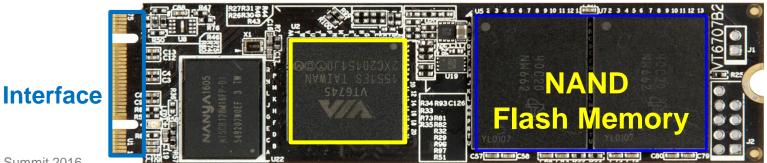
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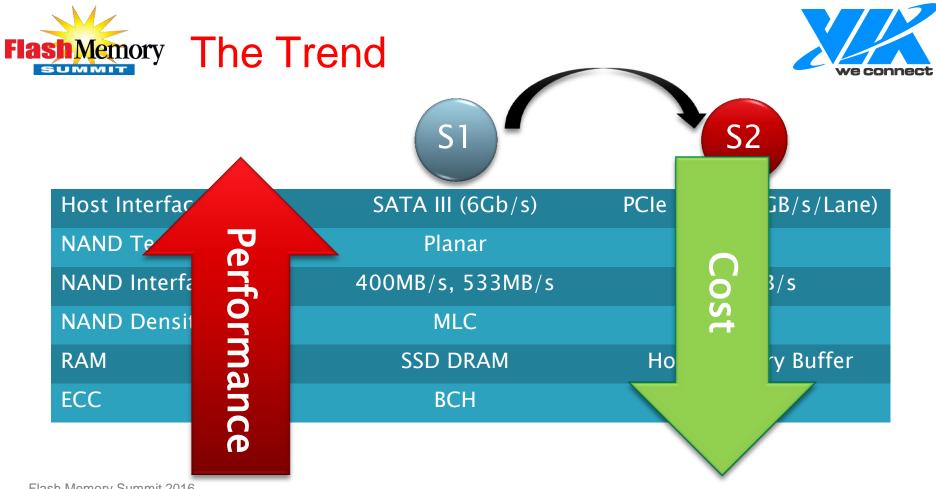






- Growing popularity of NAND flash memory and SSD:
  - High read/write performance
  - Low power consumption
- SSD has changed the storage landscape on a wide range of applications: from embedded devices to data center.









### • The bridge between the host and the storage media.







Minimize	Maximize
Recovery Time	Parallelism
CPU Overhead	Garbage Collection Efficiency
Write Amplification	Wear Leveling Efficiency
Data Loss	
Latency	





### • Parallelism

- Multi-plane operations (internal)
- Multi-channel architecture (external)
- Write amplification
  - o Garbage collection is the main contributors
  - Write workloads





### Multi-channel interleaving

Grouping blocks into a superblock

 D. Jung et al., "Superblock FTL: a superblock-based flash translation layer with a hybrid address translation scheme," ACM Transactions on Embedded Computing Systems, vol. 9, no. 4, 2012

 B. Peleato et al., "Analysis of trade-offs in v2p-table design for NAND flash," Asilomar 2012

### Superblock FTL: A Superblock-Based Flash Translation Layer with a Hybrid Address Translation Scheme

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In NAND flash-based storage systems, an intermediate software layer called a Flash Layer (FTL) is usually employed to hide the erase-before-write characteristics of memory. We propose a novel superblock-based FTL scheme, which combines a se logical blocks into a superblock. In the proposed Superblock FTL, superblocks are man granularity, while pages inside the superblock are mapped freely at fine granularity to in several physical blocks. To reduce extra storage and flash memory operations, I mapping information is stored in the spare area of NAND flash memory. This he translation scheme has the flexibility provided by fine-grain address translation, w the memory overhead to the level of coarse-grain address translation. Our experime the trade-off that they offer in terms of complexity, write show that the proposed FTL scheme significantly outperforms previous block-mapped with roughly the same memory overhead.

Categories and Subject Descriptors; D.4.2 [Operating Systems]; Storage Mana ondary storage; B.7.1 [Integrated Circuits]: Types and Design Styles-Memory te

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#### ANALYSIS OF TRADE-OFFS IN V2P-TABLE DESIGN FOR NAND FLASH

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#### ABSTRACT

Flash memory uses relocate-on-write, also called out-of-place write for performance masons. Data files from the host are spread across several non-sequential NAND physical pages. In order to retrieve host data at a later point a virtual-tophysical address table mapping the files to their physical addresses must be maintained. This process entails two basic steps. The first is to divide the NAND physical space in a hierarchical manner for efficiency of address lookup. The second is to store the resulting address lookup table, also called a virtual-to-physical (V2P) table in an efficient manner on the flash. This paper explores different architectures for constructing such table and storing it, thereby characterizing speed, and endurance of the flash memory

#### 1. INTRODUCTION

NAND-flash has unique characteristics that pose challenges to the SSD system design. The basic unit of NAND physical space is a block, consisting of a fixed number of pages, typically 64 pages of 4 KB each. A block is the elementary unit for erase operations, whereas reads and writes are processed in terms of pages. Before data can be written to a page (i.e., the page is programmed with that data), the block must have been erased. Moreover, NAND flash memories have a limited program-erase (PE) cycle count, or equivalently there is a limit to the number of times information can be re-written. Flash memory uses relocate-on-write, also called out-ofplace write [8], mainly for performance reasons: If write-inplace is used instead. flash will exhibit high latency due to the necessary reading, erasing, and re-programming of the entire

block in which data is being updated. However, relocate-onwrite requires maintaining a virtual-to-physical (V2P) table mapping the files to their physical addresses. This process entails two basic steps. The first is to divide the NAND physical space in a hierarchical manner for efficiency of address lookup. The second is to store the V2P table in an efficient manner on the flash. The architecture used for constructing such table and storing it plays a significant role in the overall performance of the memory

Additionally, relocate-on-write requires a garbage-collection rocess involving additional read and write operations [4]. This effect is known as write amplification and it reduces both endurance and write throughput [6]. Different garbage collection policies result in different write amplification per formance. Here, endurance refers to the lifetime of the memory and write throughput refers to the rate at which incoming host data is transferred to Flash memory.

Write amplification, which depends on overprovisioning can be reduced by writing sequentially, since any file is then condensed in a small number of blocks. Additionally, when a file, or a portion thereof, occupies physically sequential pages, it can be located using only its starting location and length. As a result, writing sequentially would also reduce the size of the virtual-to-physical address table (V2P-table) mapping the files to their physical addresses. However, spreading the file across several blocks allows for faster reading and writing, since different blocks can be read in parallel via different channels. Additionally, the latter provides better error protection: if a block gets corrupted or loses information due to passage of time, the errors are spread across several files, and hence any single block can be corrected using a small amount of redundancy for each file

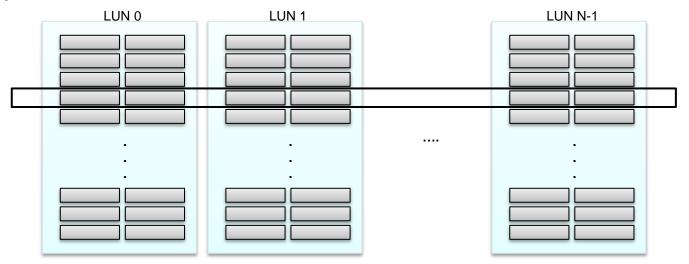
Another important factor to consider is wear leveling. The program and erase operations damage the dielectric barrier in the flash cells, until they reach a point in which they can no longer store information reliably. When a certain number of the blocks reach this point, the memory is considered dead. If a subset of blocks are programmed and erased more often than the others they will suffer more damage and die earlier, effec tively decreasing the lifetime of the memory. In practice, it is common for a memory to store both cold data, which is very rarely undated and hot data, which is undated often. Blockstoring hot data are programmed and erased more often than those storing cold data. Wear leveling algorithms are therefore used to increase the memories' lifetime by occasionally moving cold data between blocks. The amount of data that needs to be moved during wear leveling, as well as how often this needs to be done depends on the architecture used. Wear

<sup>1</sup>Overprovisioning is defined as the difference between the total space in the drive and the user-accessible space, normalized by the user-accessible





• Block management is based on the granularity of a superblock.



Flash Memory Summit 2016 Santa Clara, CA Across Channels





### • Pros:

- Superblock spans multiple channels for concurrent write.
- o Block management overhead is reduced.
- Conductive to RAID 5 implementation.

### Cons:

GC efficiency depends on data locality (hot/cold and sequential/random data).



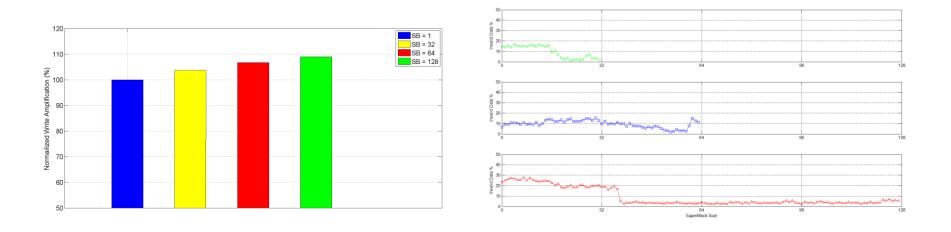


- Over-Provisioning
- I/O applications
- GC efficiency
- Data integrity writes
- Hot and cold data separation:
  - Algorithm (internal)
  - Host hints (external)





### • Workload: 4K random write with 18% hot data.





## **Real Workload Traces**



### Write Off-Loading: Practical Power Management for Enterprise Storage

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#### Abstract

In enterprise data centers power usage is a problem impacing server density and the total cost of ownership. Storage uses a significant fraction of the power budget and there are no widely deployed power-saving solution lives is for enterprise storage systems. The traditional view is that enterprise workloads make spinning disks down ineffective because idle periods are too short. We analyzed block-level traces from 36 volumes in an enterprise data center for one week and concluded that significant idle periods exist, and that they can be further increased by modifying the read/write patterns using write ant storage elsewhere in the data center.

The key challenge is doing this transparently and efficiently at the block level, without sacrificing consistency or failure resilience. We describe our write offloading design and implementation that achieves these goals. We evaluate it by replaying portions of our traces on a rack-based testbed. Results show that just spinning disks down when idle saves 28–36% of energy, and write off-loading further increases the savings to 45–60%.

#### 1 Introduction

Power consumption is a major problem for enterprise data centers, impacting the density of servers and the total cost of ownership. This is causing changes in data center configuration and management. Some components already support power management features: for example, server CPUs can use low-power states and dynamic clock and voltage scaling to reduce power consumption significantly during idle periods. Enterprise storage subsystems do not have such advanced power in the data center [32]. An enterprise grade disk such as the Seaguate Cheetah 15.K.4 consumes 12.W even when idle [26], whereas a dual-core Intel Xeon processor consumes 24 W when idle [14]. Thus, an idle machine with one dual-core processor and two disks already spends as much power on disks as processors. For comparison, the 13 core servers in our building's data center have a total of 179 disks, more than 13 disks per machine on average. Saving power in storage systems is difficult. Simply buying fewer disks is usually not an option, since this would reduce peak performance and/or capacity. The alternative is to spin down disks when they are not in use. The traditional view is that idle periods in server workloads are too short for this to be effective [5, 13, 32]. In this paper we present an analysis of block-level traces of storage volumes in an enterprise data center, which only partially supports this view. The traces are gathered from servers providing typical enterprise services, such as file servers web servers, web caches, etc.

Antony Rowstron

Previous work has suggested that main-memory caches are effective at absorbing reads but not writes [4]. Thus we would expect at the storage level to see periods where all the traffic is write traffic. Our analysis shows that this is indeed true, and that the request stream is write-dominated for a substantial fraction of time.

This analysis motivated a technique that we call write off-loading, which allows blocks written to one volume to be redirected to other storage elsewhere in the data center. During periods which are write-dominated, the disks are span down and the writes are redirected, causing some of the volume's blocks to be off-loaded. Blocks are off-loaded temporarily, for a few minutes up to a few hours, and are reclaimed lazily in the background after the home volume's disks are span up.

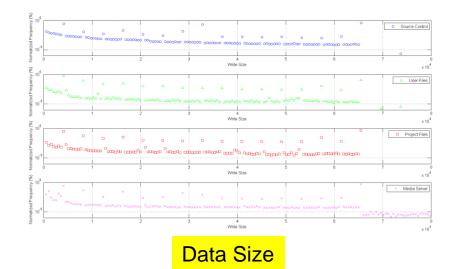
Write off-loading modifies the per-volume access paiterns, creating idle periods during which all the volume's disks can be spun down. For our traces this causes volumes to be idle for 79% of the time on average. The cost of doing this is that when a read occurs for a nonoff-loaded block, it incurs a significant latency while the disks spin up. However, our results show that this is rare.

Server	Function
usr	User home directories
proj	Project directories
prn	Print server
hm	Hardware monitoring
rsrch	Research projects
prxy	Firewall/web proxy
src1	Source control
src2	Source control
stg	Web staging
ts	Terminal server
web	Web/SQL server
mds	Media server
wdev	Text web server

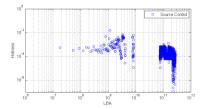
 D. Narayana et al. "Write off-loading: practical power management for enterprise storage," ACM Transactions on Storage, Vol. 4 Issue 3. 2008.

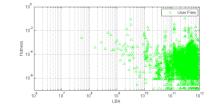


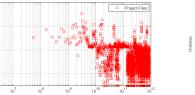
## Flash Memory Write Workload Characteristics

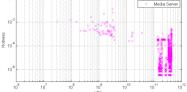


### **Data Hotness**



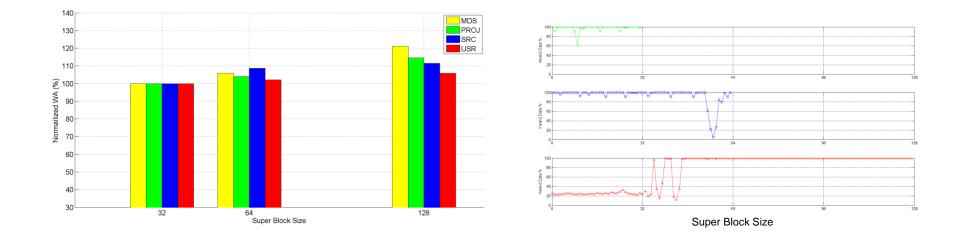








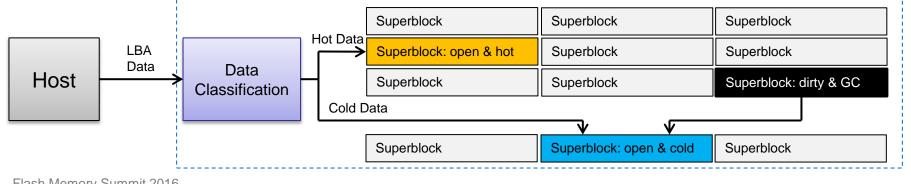






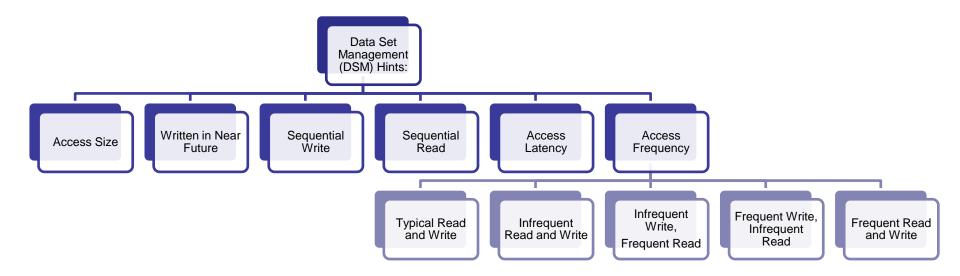


- Logical block addressing (LBA):
  - Frequency: hot/cold data
  - Recency: workload changes
- Hot and cold data separation













## Host Hints: Other Interface



### The Multi-streamed Solid-State Drive

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### Abstract

This paper makes a case for the multi-streamed solidstate drive (SSD). It offers an intuitive storage interface for the host system to inform the SSD about the expected lifetime of data being written. We show through experimentation with a real multi-streamed SSD prototype that the worst-case update throughput of a Cassandra NoSQL DB system can be improved by nearly 56%. We discuss powerful use cases of the proposed SSD interface.

### 1 Introduction

NAND flash based solid-state drives (SSDs) are widely used for main storage, from mobile devices to servers to supercomputers, due to its low power consumption and high performance. Most SSD users do not (have to) realize that the underlying NAND flash medium disallows in-place update; the illusion of random data access is of fered by the SSD-internal software, commonly referred to as flash translation layer or FTL. The block device abstraction paved the way for wide adoption of SSDs because one can conveniently replace a HDD with an SSD without compatibility issues.

Unfortunately, maintaining the illusion of random data access through the block device interface comes at costs. For example, as the SSD is continuously written, the underlying NAND flash medium can become fragmented. When the FTL tries to reclaim free space to absorb further write traffic, internal data movement operations are incurred between NAND flash locations (i.e., garbage collection or GC) [6], leaving the device busy and sometimes unable to properly process user busy and sometimes unable to properly process user days of specific and the sultant changing performance behavior of a given SSD is hard to predict or reason about, and remains an impediment to full-system optimization [1].

In order to address the problem from the root, we propose and explore *multi-streaming*, an interface mechanism that helps close the semantic gap between the host system and the SSD. With the multi-streamed SSD, the host system can explicitly open "stream" in the SSD and send write enguests to different streams according to their expected lifetime. The multi-streamed SSD then ensures that the data in a stream are not only written together to a physically related NAND flash space (e.g., a NAND flash block or "erase unit"), but also separated from data in other streams. Ideally, we hope the GC process would find the NAND capacity unfragmented and proceed with no costly data movements.

In the remainder of this paper, we will delve first into the problem of SSD aging and data fragmentation in Section 2, along with previously proposed remedies in the literature. Section 3 will explain our approach in detail. Experimental evaluation with a prototype SSD will be presented in Section 4. Our evaluation looks at Cassandra [7], a popular open-source key-value store, and how an intuitive data mapping to streams can significantly improve the worst-case throughput of the system. We will conclude in Section 5.

### 2 Background

### 2.1 Aging effects of SSD

SSD aging [16] explains why the SSD performance may gradually degrade over time; GC is executed more frequently as the SSD is filled with more data and fragmented. Aging effects start to manifest when the "clean" NAND flash capacity is consumed, and in this case, the FTL must proactively recover a sufficient amount of new capacity by "erasing" NAND flash blocks before it can digest new write data. The required erase operations are often preceded by costly GC; to make matters worse, a NAND block, a unit of erase operation, is fairly large in modern NAND flash memory with 128 or more pages in it [15]. When the SSD is filled up with more and more data, statistically, the FTL would need to copy more valid pages for GC before each NAND flash erase operation. This phenomenon is analogous to "segment cleaning" of a log-structured file system [13] and is well studied.

Proposed by Samsung.

- A storage interface to inform (hint) SSDs about the data.
- The host system opens "streams" for different write requests.
- Data in a stream is written together to a related physical NAND flash space and separated from the data in other streams.
- J. Kang et al. "The multi-streamed solid-state drive," Proceedings of 6<sup>th</sup> USENIX conference on Hot Topics in Storage and File Systems, 2014.



# Host Hints: Other Interface

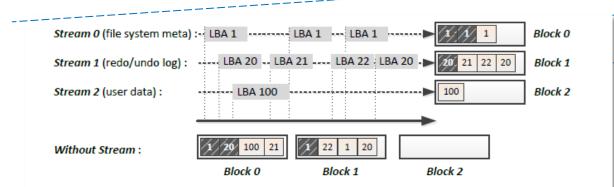
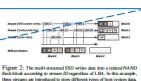


Figure 2: The multi-streamed SSD writes data into a related NAND flash block according to stream ID regardless of LBA. In this example, three streams are introduced to store different types of host system data.

J. Kang et al. "The multi-streamed solid-state drive,"

Proceedings of 6<sup>th</sup> USENIX conference on Hot Topics in Storage and File Systems, 2014.

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Both the host system and the SSD share a unique stream / core Intel i7-3770 3.4GHz processor. We turned off ID for each open stream, and the host system augments/ each write with a proper stream ID. A multi-streamed SSD allocates physical capacity carefully, to place data in a stream together and not to mix data from different streams. Figure 2 illustrates how this can be achieved. We believe that the multi-stream interface is abstract enough for the host system to be able to tap, with convincing use cases and results (as discussed in Section 4). Furthermore, the level of information delivered through the interface is concrete enough for the SSD to optimize its behavior with. There are other proposals to specify write data attributes, like access frequency [11]. However, it is not straightforward for the SSD to derive data

### 3.2 Implementation

We implemented the proposed multi-stream interface on the currently marketed Samsung 840 Pro SSD [14]. Because 840 Pro is based on the SATA III interface, we piggyback stream ID on a reserved field of both regular and queued write commands as specified in the AT attached (ATA) command set [5]. Our multi-streamed SSD prototype currently supports four streams (Stream 1 to 4) on top of the default stream (Stream 0),

lifetime from the expected frequency of data updates.

We modified the Linux kernel (3.13.3) to have a con-Auit between an application and the SSD, through the file system and the layers below. More specifically, an application passes a stream ID to the file system through the fadvise system call, which, in turn, stores the stream ID in the inode of the virtual file system. When dirty pages are flushed into the SSD, or the application directly requests a write operation with the direct I/O facility, we send along the write request the stream ID (that can be retrieved from the associated inode).

### 4 Evaluation

#### 4.1 Experimental setup

To evaluate the multi-streamed SSD, we conduct experiments that run Cassandra [7] (version 1.2.10), a widely deployed open-source key value store. All experiments were performed on a commodity machine with a quad-



	system	am ID As Commi	t- flushed	compaction
	-	Log	data	data
Normal	0	Ō	0	0
Single	0	1	1	1
Multi-Log	0	1	2	2
Multi-Data	0	1	2	3~4
Ratio of written	1.0	48.6	31.3	4.4,
data (%)				14.7

power management for reliable measurements.

Cassandra optimizes I/O traffic by organizing its data set in or append-only "sorted strings tables" (SSTables) in disk. New data are first written to a commit log (CommitLog) and are put in a table in the main memory (MemTable) as they are inserted. Contents in the MemTable are flushed to a SSTable once they accumulate to a certain size. Since SSTables are immutable, several of them are "compacted" periodically to form a new (large) SSTable to reduce the space and time overheads of maintaining many (fragmented) SSTables. As the compaction process repeats, valid data gradually move from a (small) SSTable to another in a different size tier. We take into account how data are created and destroyed in Cassandra when we map writes to streams.

Table 1 lists four different mappings that we examine. Normal implies that all data are mapped to the default stream (Stream 0), equivalent to a conventional SSD with no multi-streaming support and is the baseline configuration. In Single, we separate all data from Cassandra into a stream (Stream 1). System data, not created by the workload itself, include the ext4 file system meta and journal data and still go to Stream 0. Multi-Log carves out the CommitLog traffic to a separate stream, making the total stream count three (including the default stream). Finally, Multi-Data further separates SSTables in different tiers to three independent streams. Intuitively, SSTables in the same tier would have similar lifetime while SSTables from different tiers would have disparate lifetime.

For workloads, we employ the Yahoo! Cloud Serving Benchmark (YCSB) [3] (0,1,4). We run both YCSB and Cassandra on the same machine, not to be limited by the 1Gb Ethernet. In addition, we limit the RAM size to 2GB to accelerate SSD aging by increasing Cassandra's flush frequency. The compaction throughput parameter of Cassandra was modified from 16 MB/s to 32 MB/s, as recommended by the community for SSD users.

4.2 Results

Figure 3(a) plots the normalized update throughput of all mapping configurations studied. We introduce a Normal configuration with the TRIM facility turned off, to gain insight about the impact of TRIM. We make the follow-





- PCIe with NVMe enables higher performance SSDs
- FTL: parallelism and write amplification management is critical
- Hot/cold data separation:
  - Data classification: adjusting with write workloads
    Host hints: NVMe and other storage interfaces
- VIA VT6745 PCIe/NVMe SSD controller with FTL turnkey solution is the best option for high performance SSDs.



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Wed, Aug. 10 8:30 ~ 10:50am	Solution for Reliable and High Performance SSD		719A
Forum M-22	SSD Flash Management for 3D		VT6
Wed, Aug. 10 3:50 ~ 6:15pm	NAND Flash Memory		
Session 302-D	High Performance FTL		
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